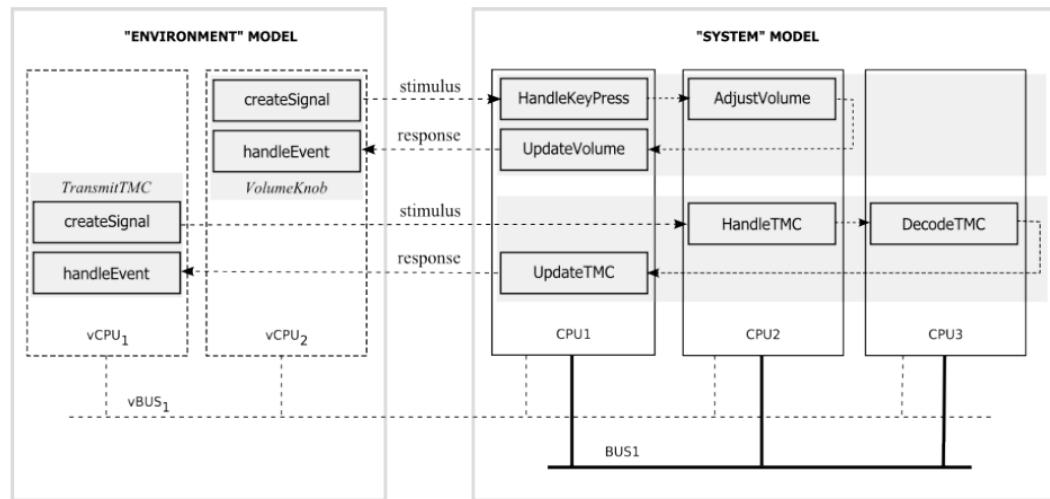


Preparing Overture for the Future – VDM10++ / VDM1X

suggestions for possible language extensions
expressiveness versus analysability

(1) Two steps forward – One step back

- virtual CPUs for all environment stimuli
(as originally proposed in FM06 paper)
- Required in order to specify multiple periodic environment processes with *independent* timing behaviors



(2) Referencing Time - A

```
class ExampleOne
```

```
operations
```

```
  op1: () ==> ()
```

```
  op1 () == skip
```

```
sync
```

```
  per op1 => time > 500
```

```
end ExampleOne
```

(2) Referencing Time - B

(reminder: #req - #act - #fin → *when* did they happen?)

```
class ExampleTwo
```

```
operations
```

```
  public static async isr : () ==> ()
```

```
  isr () == skip
```

```
  -- specify the ISR response time latency
```

```
  pre time(#act(isr)) – time(#req(isr)) < 50
```

```
  -- specify the ISR maximum elapse time
```

```
  post time(#fin(isr)) – time (#req(isr)) < 150
```

```
end ExampleTwo
```

(3) Specifying Sporadic Threads

- Periodic threads are now specified with 4-tuple (p, j, d, o)
- How to specify sporadic threads? Use $(\mathbf{nil}, \mathbf{nil}, d, \mathbf{nil})$?

```
class ExampleThree
```

```
operations
```

```
  op1 : () ==> ()
```

```
  op1 () == skip
```

```
threads
```

```
  sporadic (100) op1
```

```
end ExampleThree
```

(4) Thread Specifications - A

- Allow multiple thread definitions per class?
- Allow initializing parameters passed to thread operation?
- Thread operation must be (or implicitly is) asynchronous?

(4) Thread Specifications - B

class *ExampleFour*

operations

public async *ptr*: **nat** ==> ()

ptr (*x*) == ...

threads

periodic (1000, 10, 10, 0) *ptr* (0);

sporadic (500) *ptr* (15)

end *ExampleFour*

(5) duration and cycles - A

- Allow general expressions instead of literals

```
class ExampleFive
```

```
operations
```

```
  public async op1: nat ==> ()
```

```
  op1 (x) == duration (10 * x) skip
```

```
end ExampleFive
```


(5) duration and cycles - B

- Allow specification of intervals
- Non-deterministic choice from interval on elaboration
- Possibly overruled by simulator global setting (i.e. normal, exponential distribution with parameters)

```
class ExampleSix
```

```
operations
```

```
  public async op1 : nat ==> ()
```

```
  op1 (x) == duration (10 * x, 20 * x) skip
```

```
end ExampleSix
```

(5) duration and cycles - C

```
class ExampleSeven
```

```
instance variables
```

```
  invoked : nat := 0
```

```
operations
```

```
  op1: nat * nat ==> nat
```

```
  op1 (x, y) ==
```

```
    ( invoked := invoked + 1;
```

```
      return if (y - invoked > x) then y - invoked else x );
```

```
  public async op2: nat ==> ()
```

```
  op2 (x) == duration (10, 100, op1) skip
```

```
end ExampleSeven
```

Not covered (but interesting!)

- Dynamic deployment (cf. Nielsen)
- Multiple communication paths between CPUs
- Faulty communications (message loss)
- Message broadcasting (multiple receivers)
- Configurable communication buffer depths
- Configurable scheduling protocols