

Towards Dynamic Reconfiguration of Distributed Systems in VDM-RT

Claus Ballegård Nielsen
Aarhus School of Engineering

Agenda

Introduction

Dynamic Reconfiguration Extension

Case Study

Future Work

The What?

- Proposal for an VDM-RT extension made to enable dynamic reconfiguration during the runtime execution.
- Dynamic reconfiguration involves
 - System reconfiguration:
 - Changing the configuration of the network topology
 - Object migration:
 - moving an object from one executable unit to another during while still maintaining the internal state and references of the object.

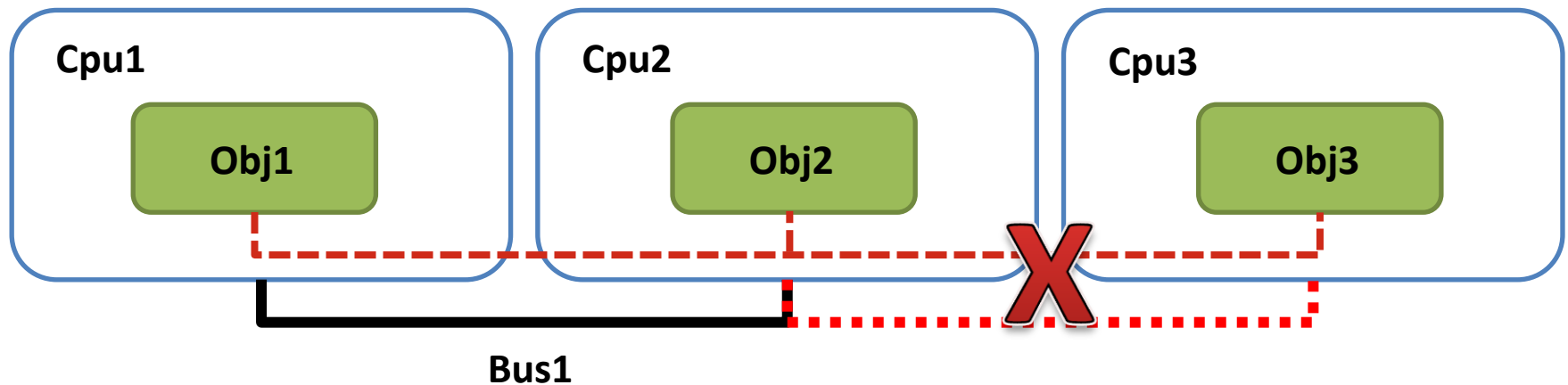
The Why?

- Newer kinds of computing systems have high demands for:
 - Adaptability, scalability and availability
- Because of:
 - Quality of service as a principal requirement
 - Recovery and failover safety measures
 - Ubiquitous behavior
 - Movement, environment change

Deployment in VDM-RT

- VDM-RT allows for the modeling of distributed real-time systems.
- The distributed system architecture is formed on the basis of two predefined classes BUS and CPU.
- The distributed system is defined in the special **system** class.
- Deployment is preconfigured and static

Deployment in VDM-RT



Dynamic Reconfiguration Extension

- Introduction of new language constructs to VDM-RT for expressing the dynamic reconfiguration.
- The proposal does not introduce any new classes or language keywords.
- Only new operations to existing predefined classes.
- The new operations are implicitly added to the three classes (**system**, **BUS**, **CPU**)

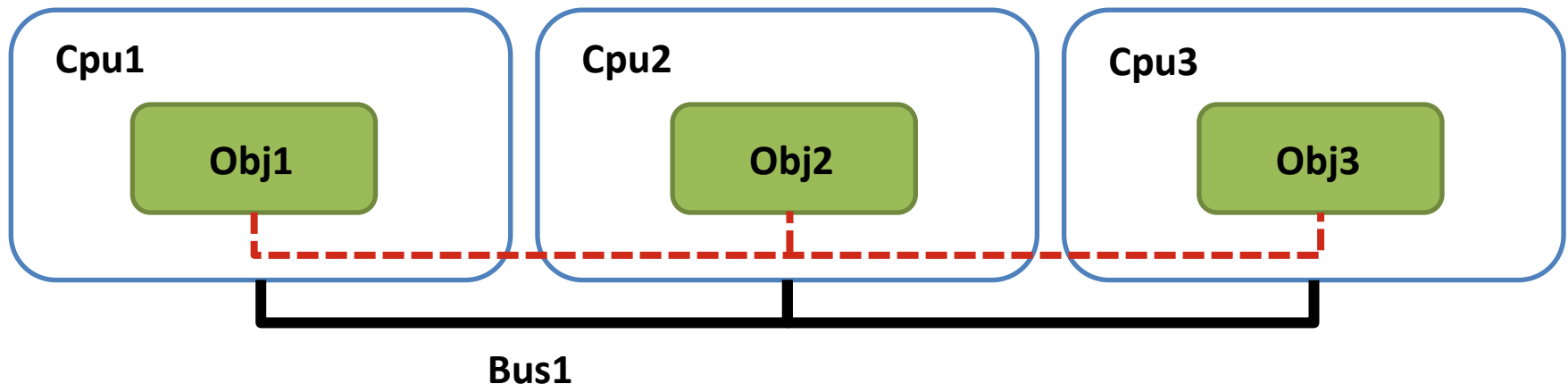
Dynamic Reconfiguration Extension

- 7 new operations
 - 2 for network reconfiguration, 1 for object migration, 4 for system status

Operation	Parameter types	Description
Sys.ConnectToBus (obj , bus)	Object * BUS	Connect object with a BUS.
Sys.DisconnectFromBus (obj ,bus, idle)	Object * BUS * boolean	Disconnect object from BUS.
Sys.Migrate (obj, cpu, idle)	Object * CPU * boolean	Migrate object to a specific cpu
Sys.ActivityOnBus (obj, bus)	Object * BUS	Determines the objects current BUS activity
Sys.IsConnected (obj, obj)	Object * Object	Are objects connected by a BUS
BusX.IsConnected (obj)	Object	Is the object connected to BusX.
CpuX.IsDeployed (obj)	Object	Is the object deployed to CpuX

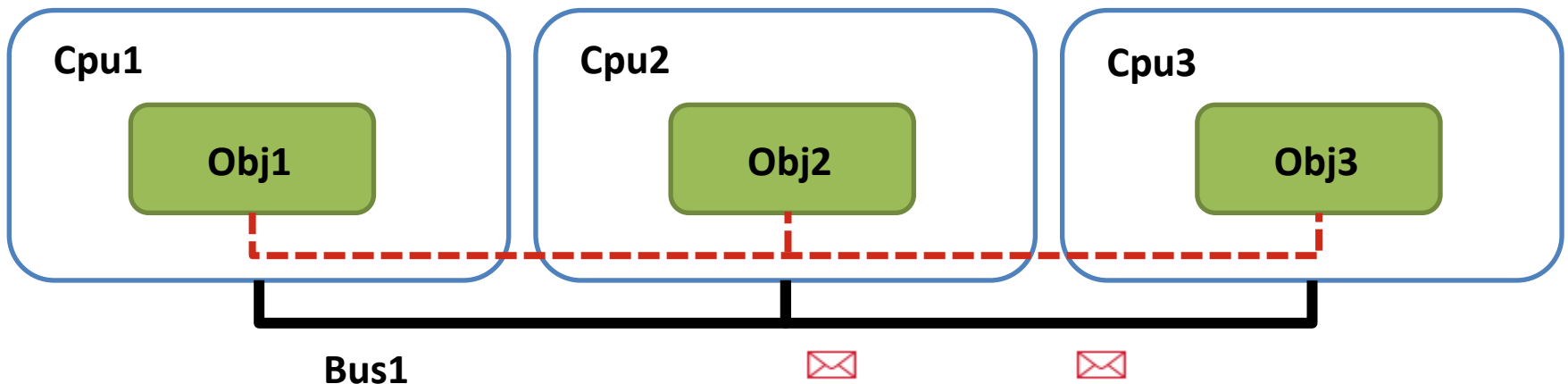
Establishing a new connection

- `Sys.ConnectToBus(obj3 , bus1)`
- Occur as an atomic operation. (uninterruptible, takes no time)
- No event or other type of notification is supplied.
- Only creates a connection from a CPU to a BUS. It does not create object references



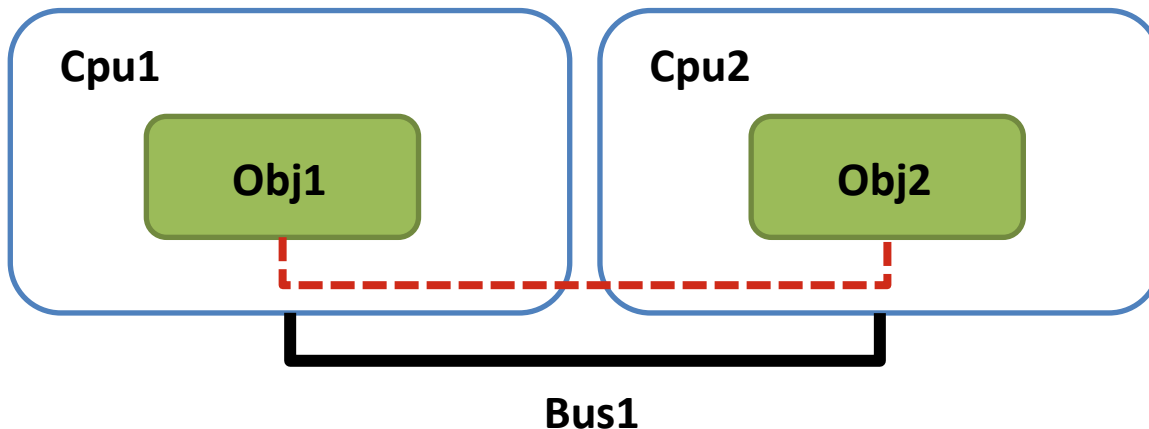
Tearing down a connection

- Atomic operation
- No graceful disconnect or notification
- Current messages will be dropped
- **Sys.DisconnectFromBus(Obj3 ,bus1, false)**
- 3. parameter indicates if the BUS should be idle before the disconnection occurs. Check is before entering atomic transaction

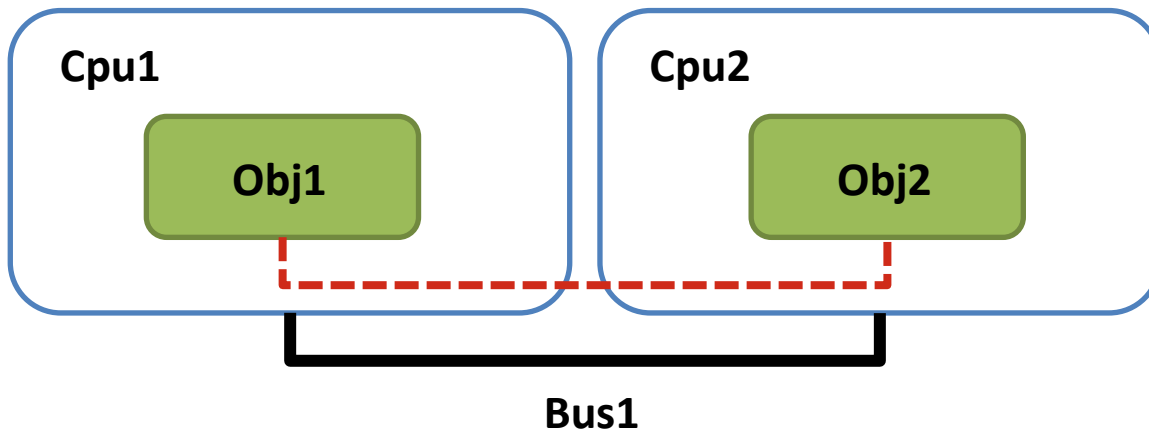
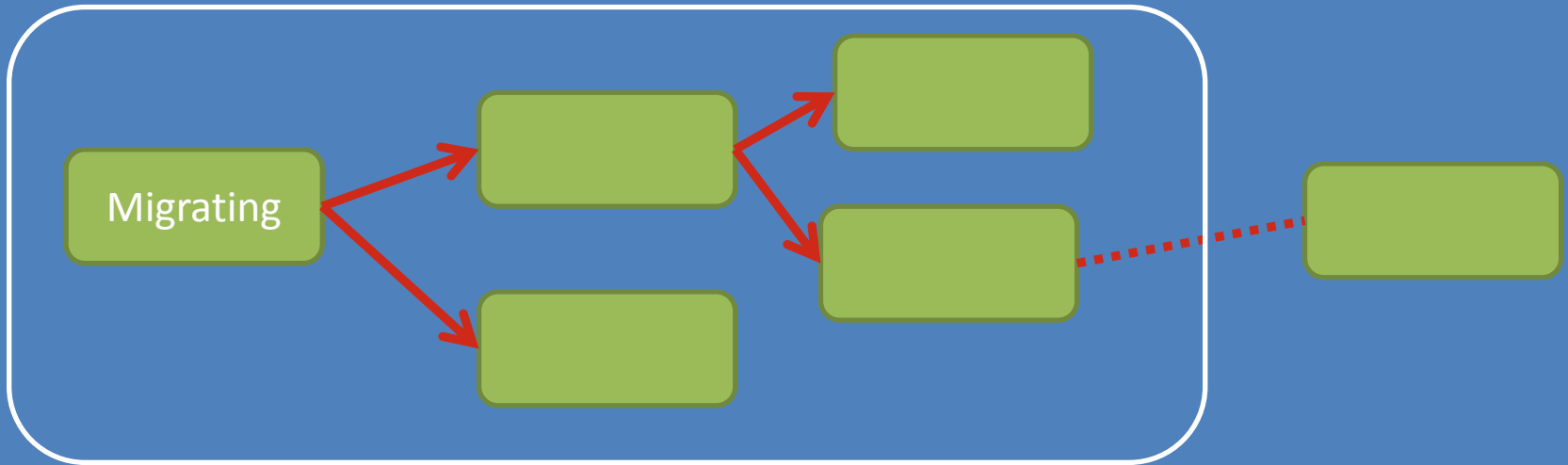


Migrate

- Moves an object to a new CPU in an atomic operation while preserving its identity and state
- Referential integrity is a challenge
 - From the object: All transitive references will be included as part of the object
 - To the object: calls may now occur over a network



Migrate

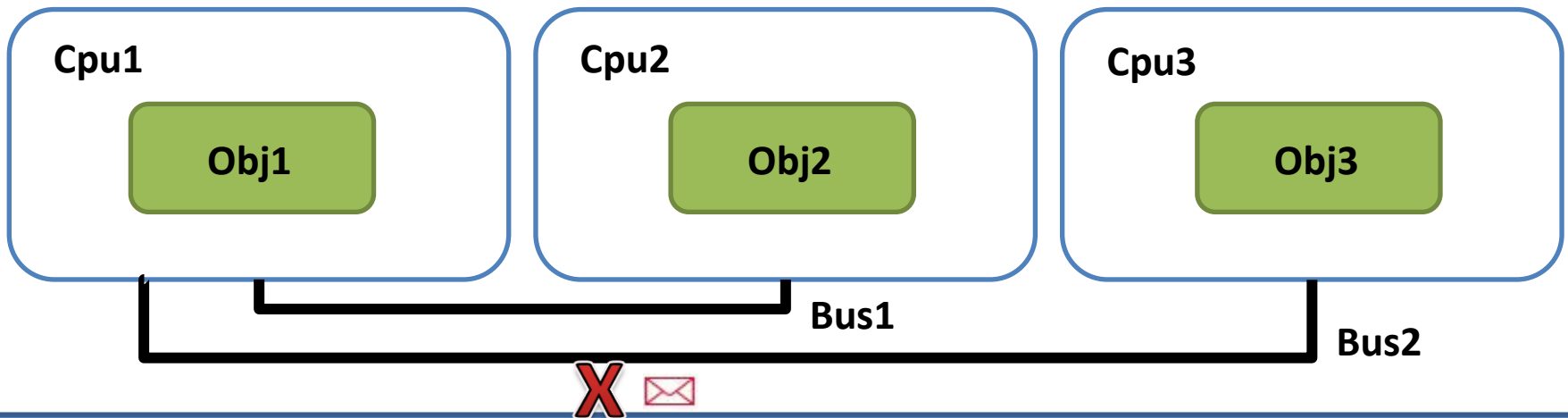


Migrate

- Moves an object to a new CPU in an atomic operation while preserving its identity and state
- Referential integrity is a challenge
 - From the object: All transitive references will be included as part of the object
 - To the object: calls may now occur over a network
- The target CPU must be connected to the same BUS as the source CPU

Migrate

- `Sys.Migrate(obj1, cpu2, false);`
- Message on the BUS that were send prior to reconfiguration will still be processed after the reconfiguration.
- Unless: the migrating object had communication with remote objects through a second BUS



Determine status

- The introduction of dynamic reconfiguration increases the need for knowledge.
- **Sys.IsConnected(obj, obj)**
- **BusX.IsConnected(obj)**
- **CpuX.IsDeployed(obj)**

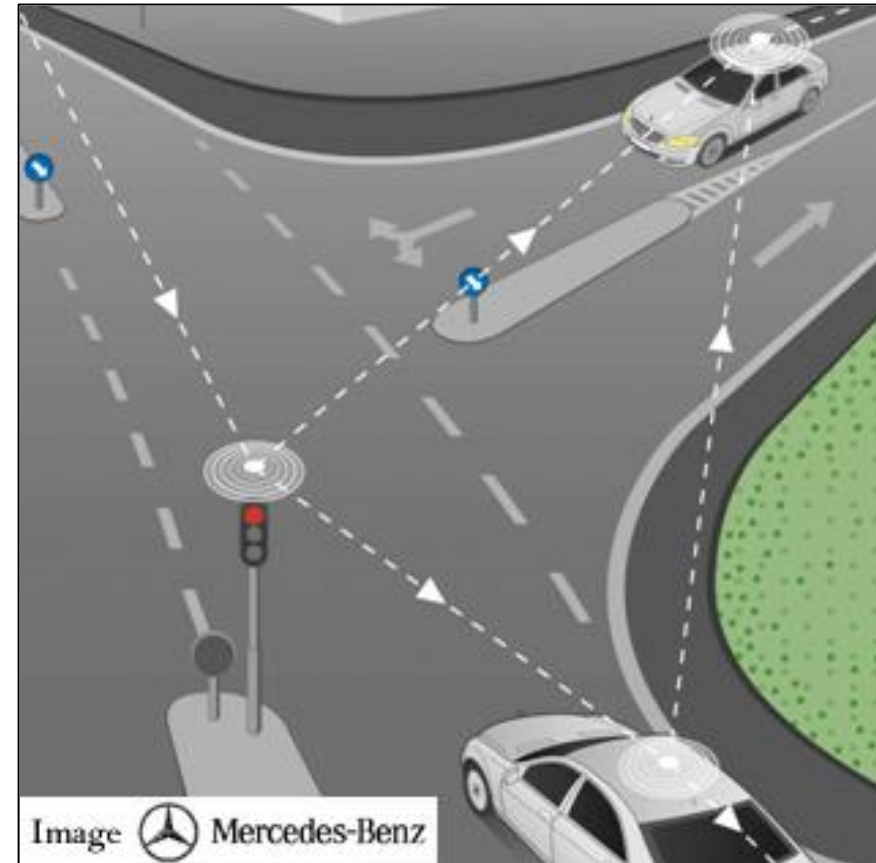
Messages on the bus

- The ActivityOnBus operation takes an object and a BUS and returns an enumerated type depicting the current activity the given object has on the given BUS.
- Idle:
 - The object has no communication on the bus.
- ProcessingRequest:
 - The object is currently processing an operation invocation by a remote object.
- WaitingForReply:
 - The object is waiting on a reply from an operation invocation on a remote object.
- RequestAndReply:
 - The object is both processing a request and waiting for a reply.

VeMo – a case study

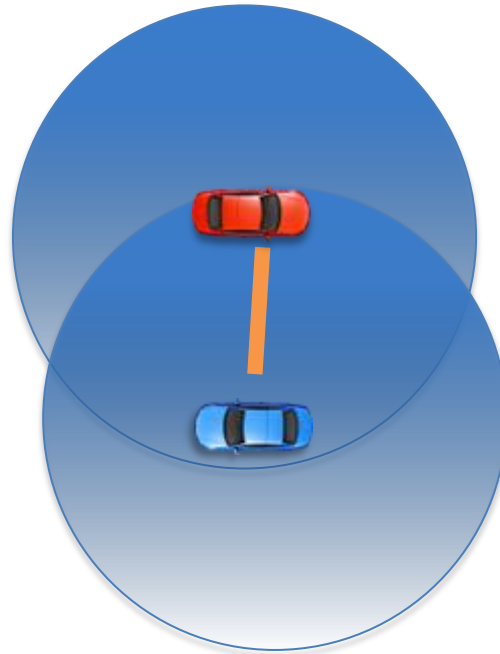
Vehicle Monitoring System

- Improve road safety
- vehicles in near proximity share information through a co-operative wireless network



VeMo – basics

- The model has a controller which calculate when vehicles are in range of each other.
- With static network topology vehicles are constantly connected.



A new challenge arise

- A large number of units with autonomous behavior can create an unpredictable number of network connections.
- Number of BUS connections available is static
 - Add dynamic creation of busses

Future Work

- Tool support for the extension by integration into Overture platform
- Investigation of the necessity for a special construct, such as a policy, for managing the dynamic reconfiguration
- A representation of messages being lost on the BUS needs to be established.
 - return value for synchronous operations.
 - exception handling
 - special type
- Dynamic creation of new BUS class instances

Q & A

